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DESIGN AND PARAMETRIC ANALYSIS OF BIOAMPLIFIER WITH HIGH CMRR AND GAIN USINGTWO-STAGE OPAMP

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ABSTRACT

OPAMP Are Used in high precision applications, OPAMP are used to attain high gain and speed. To achieve these two requirements mostof

the topologies suffer tradeoffs. An improved cascoded circuit is introduced in this work. The simulated result has an improved CMRR and Gain reducing the noise at the output. Using this topology we can achieve a gain of 80 dB with a high CMRR and phase margin achieved is 78° . Circuit is designed using cadence virtuoso 0.18 um CMOS technology.

KEYWORD: CMRR (Common moderejection ratio), NN(Normal PMOS Normal NMOS), SS(Slow NMOS Slow PMOS), SF(Slow PMOS Fast NMOS), FS(Fast PMOS Fast NMOS), FF(Fast PMOS Fast NMOS).

I. INTRODUCTION

Cascaded topology is used because it has control on the frequency behavior. Increasing the number of stacked transistor, resistance of the output stage is increased thus setting more gain. As the application of this OPAMP is inbiomedical field so the ICMR and PSRR must be sufficient. Cascoded topology increases PSRR and leads to wider ICMR and/ or smaller power supply requirements. Power supply for this application is 3.3 V. So the OPAMP must consume a small amount of power. To again ensure that the OPAMP is able to respond quickly enough to the inputs changing, a slew rate of at least 15V/us with a 5 pF load was selected. Differential trans conductance stage forms input andprovides the conversion from differential input to single ended output. First stage is followed byanother gain stage. Total gain of theOPAMP circuitry is the product of no of gain stages are used. Data Conversion is an application of OPAMP in which it drives a small capacitive load, so here buffer is not

used. If OPAMP drives a resistive load, a large capacitive load or a combination of both output buffers is used.

II. Circuit topology

The cascade OPAMP used can be used as a single stage as well as in two-stage. In the OPAMP implementation of this type of amplifier a differential pair is used as the first or the input stage and nd2 stage is a simple common source amplifier. A balanced differential inputamplifier is used. The number of PMOS and NMOS transistors in this topology is equal excluding the bias transistor. The drain of the NMOS group in differential amplifier is connected with drain of current source load PMOS group. The goal of this topology is to achieve the simplicity small size of a two-stage amplifier, wile achieving a higher gain. A balanced self-bias circuit is designed employing six transistors with aconstant gm. To provide biasing to the followed stages the main benefit of this topology is that the cascaded transistor in this design serve to increase the output resistance of the circuit, which increase the output the small signal gain of the amplifier. Terminologies associated with OPAMP-

Low Frequency Open Loop Gain Aodc: Open loop gain at low frequency of OPAMP is given as the product of each stage gain, i.e Aodc=A1.A2=gmn.(Ron||Rop) .gmp.Rop. Here the cascaded NMOS load is assumed to be much higher thanPMOS in second stage.

Input Common Mode Range: Operational amplifier uses two or threegain stages. First gain stage would always be a differential amplifier .sothe common mode range for operational amplifier is similar to that of differential amplifier and is givenby-

VCMAX=Vdd++VTHN (1) & VCMIN=VGS1,2+2.Vdsat (2)

Power Dissipation: The current supplied by the constant current determines power Dissipation by theOPAMP sources multiplied by Vdd.

Output swing and Current Sourcing

Sinking Capability: The common source amplifier used in the operational Amplifier determine the output swing. In above two stages OPAMP the maximum output swing is limited by M7 when M7 goes to triode region. The minimum output voltage swing is determined by M8 when M8 goes to triode region. The high gain region fall between output voltages of these two voltages.

Offsets: When a transistor is sized, it make sure that it is sized to source a constant bias current to keep that transistor always in saturation. But when the width of transistor is increased to source a higher current than the transistor will move to triode region and the output voltage will approximately be equal to Vdd. So the transfer curve will get a shift or offset.

Compensating The OPAMP: Theamount of output that is fedback is called feedback factor. It is denoted by

(CMRR): CMRR is calculated in same way as the differential amplifier. The common mode gain of diff_amp is A_c. The common mode gain of OPAMP is A_c A₂. The differential gain of OPAMP is AdA2. So the CMRR of OPAMP is given in dB by β Or $\beta = R2/(R1+R2)$. The largest value of β occur when all of the output is feedback to OPAMP input. Whenclosed loop gain is larger,!(feedback factor) will be smaller i.e less output signal will be fedback and OPAMP circuit will be stable.

Gain and Phase Margin: When load capacitance varies, the stability will be affected. Further with changes in temperature, process, and power supply, the stability of OPAMP gets affected. Gain margin and phase margin is used to specify how stable is the OPAMP at given operating conditions. Phase margin is the phase shift that is calculated at unity openloop gain.

Common Mode Rejection Ratio (CMRR): CMRR is calculated in same way as the differential amplifier. The common mode gain of diff_amp is Ac. The common mode gain of OPAMP is Ac A2. The differential gain of OPAMP is AdA2. So the CMRR of OPAMP is given in dB by

Power Supply Rejection Ratio(**PSRR**): The power supplyrejection ratio describes how well an amplifier rejects noise.

$$PSRR^{+} = Aol(f)/vout/v^{+}$$
(4)
$$PSRR^{-} = Aol(f)/vout/v^{-}$$
(5)

Design specification	Values
DC gain	>100dB
Phase margin	$>60^{0}$
Bandwidth	>100MHz
Cload	50pf
V _{ICMR}	ICMR= $+1.5V$,
	ICMR=-1.5V
Power dissipation	<100uW
Slew Rate	V/us
Supply voltage	1.65V

Table 1: Required Specifications For OPAMP.

III.Proposed and Designed Circuit With Cascoded Second Stage

This OPAMP is balanced because drain to ground loads for M1 and M2 are same.



Fig. 1: A Balanced Two Stage OPAMP Using A Cascoded OutputStage.^[26]

For a balanced cascoded output stage the design relationships are-

Slew rate = Iout/CL

Gain Bandwidth=(gm1gm8)/gm3CL

 $Av=1/2\{(gm1gm8/gm3)+(gm2gm6/gm4)\}R_{02}$

Vin max=Vdd- $(I5/\beta 3)^{1/2}$ -|Vto3|(max)+Vt1(min)

 $V_{in}(min) = V_{ss} + V_{ds5} + (I_5/\beta_1)^{1/2} + V_{t1}(min)$

Table 2:	Transistor	Sizing.
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S.NO.	Transistor	W/L Ratio
1.	S1, S2	12
2.	S3, S4	16
3.	S5	7
4.	S6, S7, S8	40
5.	S9, S10,S11,S12	18.2
6.	S13	8.75
7.	S14, S15	40



Fig. 2: Schematic of Proposed BioAmplifier.

IV. Designed Amplifier Results



Fig. 3: Transient response.

Gain and Phase Margin

The gain margin is factor that determines the stability of system. It is the gain in that need to be increased ina closed loop system. Gain and phase plot is shown in fig 4.12. Gain margin is Gain value in dB that is calculated from the plot for the phase equal to 180° . From the plot calculated gain margin is 6dB which show that the system is stable. Here we can double the gain without the system being unstable. Phase margin is calculated at the unity gain frequency. From the plot the PM is calculated as 78° . If phase margin is greater than 30° than the system is good. For a PM= 0° the system is neutrally stable. For unstable open loop

system, PM and GM gives confusing results. PM and GM determines that how much uncertainties an open loop system can tolerate before the closed loop system goes unstable. PM is related to the damping overshoot of the system. For small PM large overshoots are produced in the system i.e. output of the system will have oscillations but response will be fast. For large PM output will have less oscillations but the response will be slow.



Fig. 4: Gain and Phase Plot for Differential Input Signal.

Phase Margin = 180-Phase shift= $180-102=78^{\circ}$



Fig. 5: Gain and Phase Plot forcommon mode input signal.

 Table 3: Simulated Values.

Design Specification	Values
DC gain	79dB
Phase Margin	78^{0}
Bandwidth	132Mhz
CLoad	1pF
VICMR	ICMR+=1.6V,ICMR-=0.8V
Power Dissipation	182uW
Slew Rate	20V/us
Supply Voltage	1.65

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V. RESULTS AND DISCUSSION

OPAMP are used in high precision applications, OPAMP are used to attain high gain and speed. To achieve these two requirements most of the topologies suffer tradeoffs. An improved cascoded circuit is introduced in this work. The simulated result has an improved CMRR and Gain reducing the noise at the output. The output noise, which is a tradeoff here. This needs to be reduced. Themaximum allowable noise power at output is 450uV. 50% of this noise is reserved for thermal noise and this willleave 225uV for other noises including jitter noise, OPAMP noise etc. More than 70% of this 225uV is due to amplifier noise. The SNR value should be higher than 70dB. Fig4 and Fig5 shows the DC gain and Phase Plot for the differential input and common mode input. The OPAMP reaches 80 dB DC gain. When the output swing increases DC gain remains constant till the output voltage clips. Phase for the differential input is calculated to 78^{0} .

Five-corner analysis simulation is done considering all the non-linearity's that occur due to process variations, variations due to fabrication, temperature effects variations etc. Table 3 shows all the simulated result of the designed amplifier. Comparing with the circuit designed using differential amplifier this amplifier has low power dissipation, and reduced area (as the number of transistors are reduced) giving same amount of DCgain and CMRR.

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